

A Flexible DL-based Architecture for Deductive Information Systems

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Background and Motivation

- Description logics (DLs) provide widely accepted standards for decidable knowledge representation
- Benefits: Scalability of expressivity, foundations for ontology languages (Semantic Web), impressive theory, performant DL systems (DLS)
- Question: A basis for ontology-based information systems (IS)?
- Evaluation: How to use and extend a DL system for building an ontology-based query answering system for city maps?
- Contribution: <u>Pragmatic solutions</u> to tackle the design, representation and query answering problem in domains for which standard DLs are not well-suited

Drawbacks of Today's DLS for IS Building

- Scalability for ABoxes not easy to achieve (see LUBM with NRQL + RACERPRO)
- Few have expressive and practical ABox QL
- Persistency for large ABoxes? Use a DB, but:
 - Query answering requires inference DB access during reasoning? Pre-loading of (which portions of the) ABox into memory?
 - Thesis: as long as RPC is much slower, representation layer should include query answering engine and reasoning engine
- ABoxes not good for "data representation" (Strings, Polygons), Concrete Domains: overkill in many cases

Underlying Thesis

- Pragmatic solutions needed for <u>todays</u> IS designers
 - Existing DLS must be reused (cannot be reimplemented in a short period of time)
 - Pragmatic ways to extend DLS in case representational deficiencies are encountered should be identified → this paper
 - Extensions must / should be easier to implement than DLS
 - Longtime perspective: DLS with "open architecture"? Plug in mechanism?
 - Even if this is achieved, extensibility is hard due to inherent intellectual complexity



Contributions

- "Road map for a difficult terrain"
- Three pragmatic settings for city maps IS
 - Setting 1: What can be done with RACERPRO ABox left alone
 - Setting 2: (RACERPRO external) spatial representation ("spatial DB") + ABox
 - Setting 3: (RACERPRO internal) spatial representation + ABox
- Base the IS on software abstractions
 - Abstract from remote vs. local procedure call
 - Abstract from ABox representation of the DLs
 - Provide more flexible means for data / information representation than ABoxes

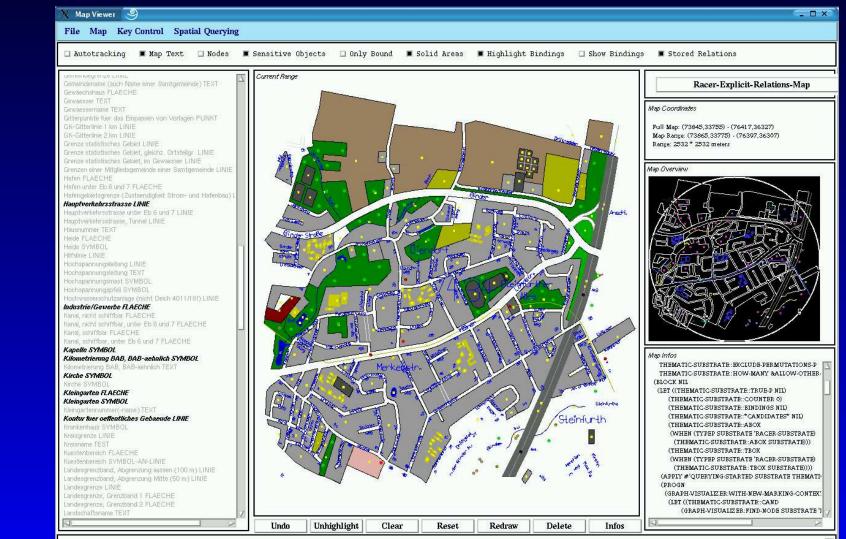


Contributions (2)

- Base the IS on software abstractions
 - Allow for hybrid representations (layering of representations)
 - Use one internal data model for the IS which allows all this: "substrate data model"
 - flexible, extensible query language needed: "substrate query language framework"
 - \Rightarrow "Semantic Middleware"
 - Thesis: flexible way to build DL-based IS
 - Example: NRQL was first external to RACERPRO; since it was implemented on top of "substrate" middleware, it could be migrated easily into RACERPRO

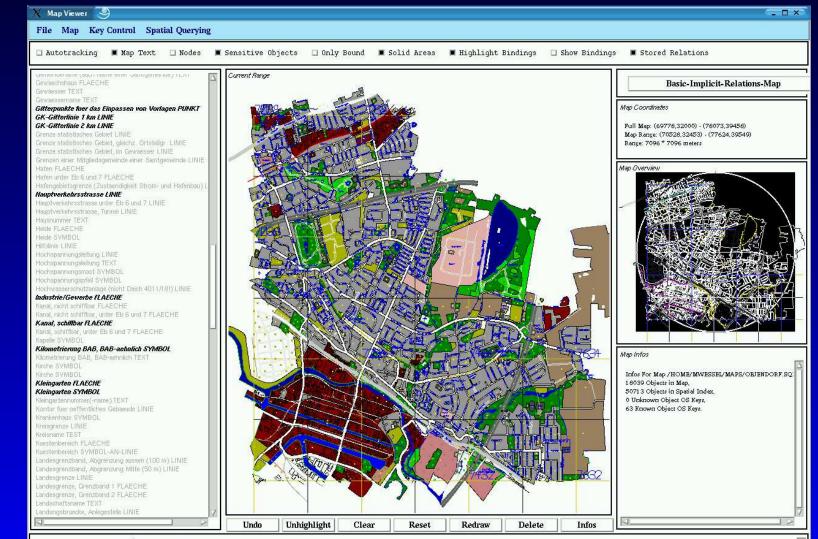
- ©"Amt für Geoinformation und Vermessung"
- Two digital vector maps in SQD format
- Objects are "classified" according to a fixed <u>list</u> of categories ("Objektschlüssel-Katalog"):
 - 5164 \Rightarrow lake, navigable, 4128 \Rightarrow meadow, 2224 \Rightarrow park, 2119 \Rightarrow living area, ...
 - Taxonomic relationships ("is-a") implicitly present, but not explicitly modeled ⇒ needs remodeling
 - Very <u>specific</u> categories, no generalizing categories: *cemetry_for_non_christians*, but *cemetry* is missing

• Map 1: 2694 geo objects, 361 primary



Command: Highlight Touching Objects Enter a SI-GEOM-THING: #<RACER-MAP-POLYGON 10973> Command:

• Map 2: 18.039 geo objects, 5.418 primary



Command: Adjust Map Extent #<BOUNDING-BOX 23C07FB4> Command: Adjust Map Center #<BOUNDING-BOX 23C07FB4> Command:

L: Adjust Map Center; M: Full Map Extent; R: Menu.

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Aspects of Geographic Data

- Two groups of aspects
 - Thematic: Geographic Category (Semantics)
 - Spatial: Area, Shape, Relationships, ...
- Space has specific properties
- Instances of spatial data types (polygons etc.) <u>automatically preserve</u> many important spatial aspects of the represented geo object (a polygon represents both shape and area)
- A map intrinsically represents spatial relationships ⇒ rich, "analogical" representation
- In an ABox, everything must be represented symbolically ⇒ "symbolic bottleneck"

Spatio-Thematic Querying

- DISK ontology in a TBox
- Remodelling of thematic DISK categories: cemetry_for_non_christians
- Additional <u>spatio-thematic</u> vocabulary: *park_with_lake* ≐ *park* □ ∃ *contains.lake*

Use spatio-thematic vocabulary in queries:
 ans(?lake, ?park, ?creek, ?industrial_area, ?chemical_plant) ←
 lake(?lake), chemically_contaminated(?lake), park(?park),
 contains(?park, ?lake), creek(?creek),
 flows_in(?creek, ?lake), crosses(?creek, ?industrial_area),
 contains(?industrial_area, ?chemical_plant),
 unreliable(?chemical_plant).



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- Representation of the map as an ABox \mathcal{A}
 - For each map object *i* with key *n*, add *i* : concept_for_key(*n*) to *A*
 - Represent dedicated metric aspects in the CD $(i : \exists (area). =_{123456})$

А

DC

A.B

EQ

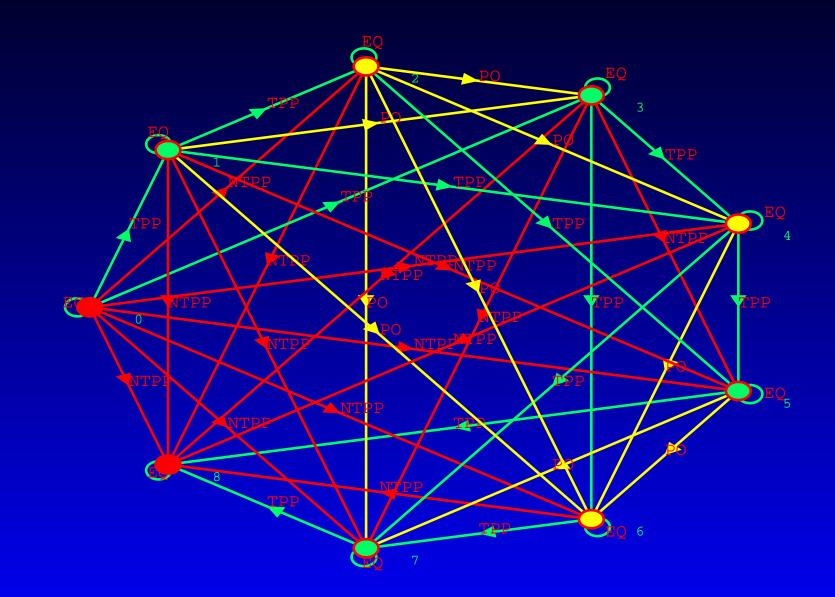
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 - ⇒ RCC8 network in the ABox (network is always <u>consistent</u>)



Illustration: DISK **ABox**



Querying the DISK (Setting 1)

- Simple spatio-thematic QL: instance retrieval queries
- concept_instances($park_with_lake$) = {i, ...}
- $i \in \text{concept_instances}(park \sqcap (\exists NTPPI.lake \sqcup \exists TPPI.lake))$
- If $\{i: park, k: lake, j: meadow, (i, j): TPPI, (j, k): NTPPI \} \subseteq A$, then also $(i, k): NTPPI \in A$ (due to map)
- RCC roles in ABox must be closed: for each i, add $i : (\leq n R) \sqcap (\geq n R)$
- $n =_{def} |\{j \mid (i,j) : R \in \mathcal{A}\}|$



Querying the DISK (Setting 1) (2)

- concept_instances($bird_sanctuary$) = {i, ...}
- $bird_sanctuary \doteq park \sqcap$ $\forall NTPPI.\neg building \sqcap \forall TPPI.\neg building$
- $\mathcal{A} \cup \{(i,k) : NTPPI\} \cup$
- $\{i: (\leq_1 TPPI) \sqcap (\geq_1 TPPI), i: (\leq_1 NTPPI) \sqcap (\geq_1 NTPPI), \ldots\} \cup$
- $\{i: (\neg park \sqcup ((\exists TPPI.building) \sqcap (\exists NTPPI.building)))\}$
 - is unsatisfiable, if {building, park, meadow} are mutually disjoint
 - Problems in the TBox: incomplete subsumption relationships (not a problem for query answering)
 - Moreover, NRQL can be used

Querying the DISK with NRQL

- NRQL offers classical negation and NAF
- For which living areas can it be proven that there are no adjacent freeways?
 ans(?living_area) ← living_area(?living_area),
 ∀adjacent.¬freeway(?living_area)
- Requires RCC closed ABox and disjointness axioms, as just discussed (not so good ...)
- Living areas with <u>no known</u> adjacent freeways? *ans*(?*living_area*) ←

 $living_area(?living_area),$

NRQL Concrete Syntax

Extentible Substrate QL Framework

- NRQL is a specialized "Substrate QL" for substrates S of type ABox
- Two kinds of atoms: unary C(x), binary R(x, y)
- x, y: Individuals, variables (with act. dom. sem.)
- Extensions of atoms on substrate S: $C(x)^{\mathcal{E}} =_{def} \{ i \mid S \models C(i) \},$ $R(x,y)^{\mathcal{E}} =_{def} \{ (i,j) \mid S \models R(i,j) \}.$
- Due to NAF: \models_{NAF} instead of \models
- Complex queries: Relational operators AND (" \times "), UNION (U), NEG (\), PROJECT-TO (π)
- New atoms can be added: \models must be defined for $S \times atom$, \Rightarrow very flexible!

Problems with Setting 1

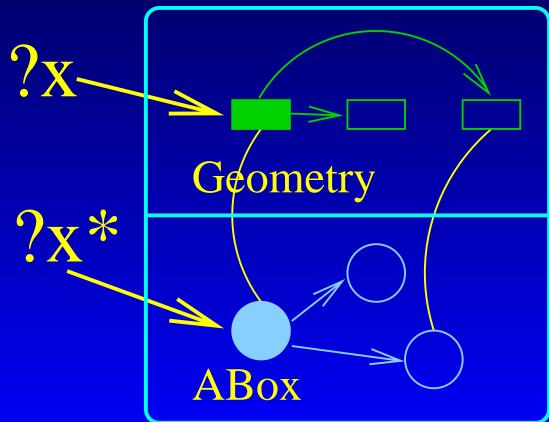
- n^2 size of generated ABoxes (29 million role assertions with *DC*, 19.880 without DC)
- Missing practically relevant query atoms (e.g., distance queries)
- Qualitative representation of "spatial data" in an ABox
- "Closed domain reasoning" requiered ⇒ missuse of the DL system (open domain reasoning)
- Geometry needed anyway, at least for presentation purposes
- ⇒ Motivates hybrid representation and query language



- Map Substrate: (*ABox*, *SBox*, *)
 - Substrate 1: ABox thematic aspects
 - Substrate 2: SBox map geometry
 - *: part. inject. mapping from nodes in S_1 to S_2



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 - Substrate 1: ABox thematic aspects
 - Substrate 2: SBox map geometry
 - *: part. inject. mapping from nodes in S_1 to S_2
- Non-symbolic spatial binary query atoms
- On-demand computation and inspection of spatial aspects
- Dedicated index structures
- \oplus Closed world reasoning in SBox
- \oplus Simple model checking
- ⇒ No more "reasoning" on spatial aspects

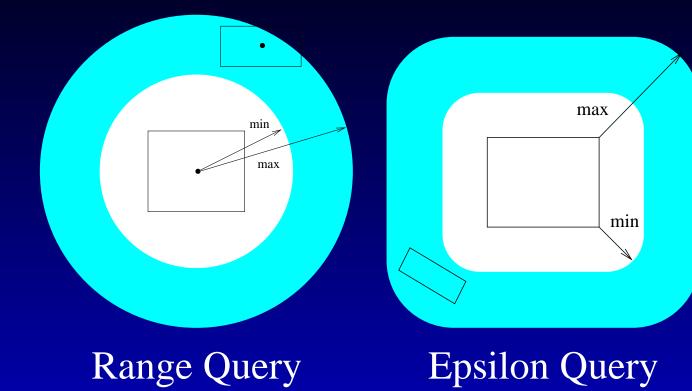


Spatial NRQL-SNRQL

- Two sorts of atoms in SNRQL
- ABox atoms:
 - Variables range over ABox individuals
 - Atoms as in NRQL (concept, role, constraint query atoms)
- Spatial atoms:
 - Variables range over SBox individuals
 - RCC atoms
 - Geometric attributes: area, length, ...
 - Metric relationships: range queries, epsilon queries, ...
- Variables are bound in parallel, bindings reflect the "*" mapping



Spatial NRQL- SNRQL



SNRQL Concrete Syntax

```
(retrieve (?*x ?*y)
  (and (?*x)
         (and living-area
             (all living-quality
                  first-class-area)))
       (?y ?x (:inside-distance 750))
       (?*y subway-station)
       (?x ?y :adjacent)
       (?*y golf-club)
       (?y (:area 1000000 nil))))
```

Hybridness can be made transparent

- Add end-user syntax for DLMAPS system: user must not be aware of the details of the map representation
- $ans(?x,?y) \leftarrow park(?x), contains(?x,?y), lake_or_pond(?y)$
- $lake_or_pond(?y) \rightarrow (lake \sqcup pond)(?*y)$
- $contains(?x, ?y) \rightarrow NTPPI(?x, ?y) \lor TPPI(?x, ?y)$

Problems with the Approach

- Theoretical problems: No spatial reasoning
- Practical problems (perspective: IS designer)
 - ABox / SBox separated, communication overhead (caches required)
 - Hybrid QL required
 - IS designers probably do not want to implement a query answering engine, thus:
 - Split hybrid query into subqueries, send to different sources, combine sub-results
 - Probably bad performance (no overall query optimization, communication overhead, combination of results, ...)
 - \Rightarrow Shows a way, but too hard to realize

Hybrid Substrates in RACERPRO

- Thus, in order to avoid these problems, this functionality should be put into the DL system
- \Rightarrow Hybrid substrates for RACERPRO
 - Makes functionality available for other IS designers
 - Compensate for representational deficiencies of the ABox
 - Data substrate: stores told value data (from CD of ABox or OWL documents, enabled retrieval facilities)
 - RCC substrate: associate an RCC network with an ABox (next) ⇒ limited form of spatial reasoning

The Data Substrate

- New sort of variables: *?x (*\$?x), ranging over data nodes
- Data nodes can also be data values in OWL documents
- Data nodes/edges have descriptive labels: kind, role, property, ...
- Notion of entailment for labels of nodes/edges
- Data query atoms are in pos. CNF & contain literals and predicates.



• Substrate QL based on notion of logical consequence: a binding to a variable is only established if this binding holds in <u>all</u> models ("certain answer")

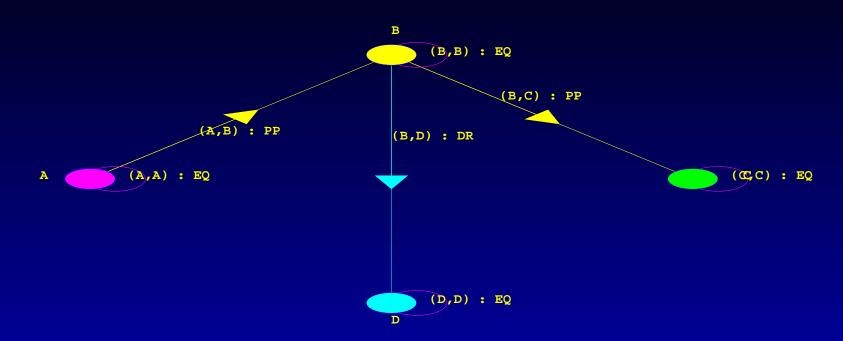


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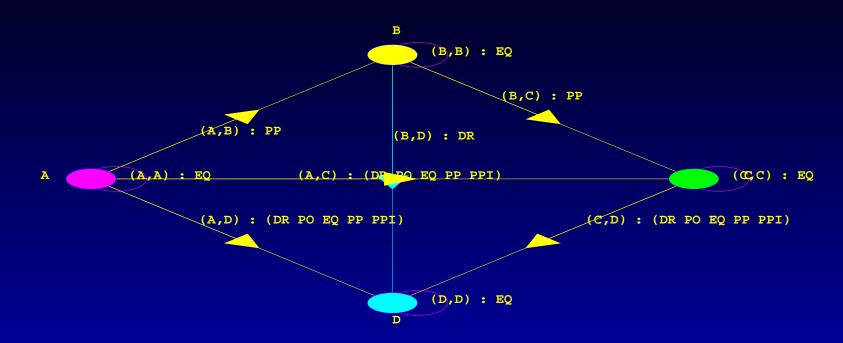


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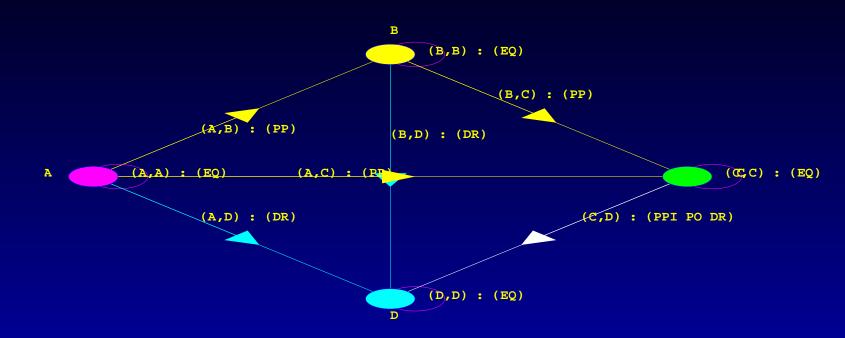




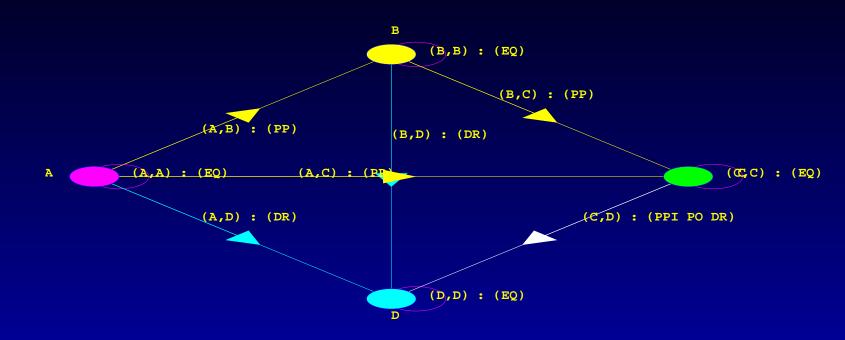












 $\models DR(A, D)$ $\models PP(A, C)$ $\models \{PPI, PO, DR\}(C, D)$ \models



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- (Proof of concept implementation)



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Conclusion

- Spatial parts from spatio-thematic concepts removed from the TBox
- Instead, spatially aware query answering instead of TBox / concept reasoning
- Simple layering of representations can be of great value in practice
- (Possibly) Hybrid substrate QL framework allows for extensibility
- Base the IS on abstractions so that the representation can be changed easily
- (Theoretically) simple techniques can be successful in practice





Thanks for your attention!

ESCOR '06, August 21th, 2006, Michael Wessel – p.27/27