





joint work with many researchers:

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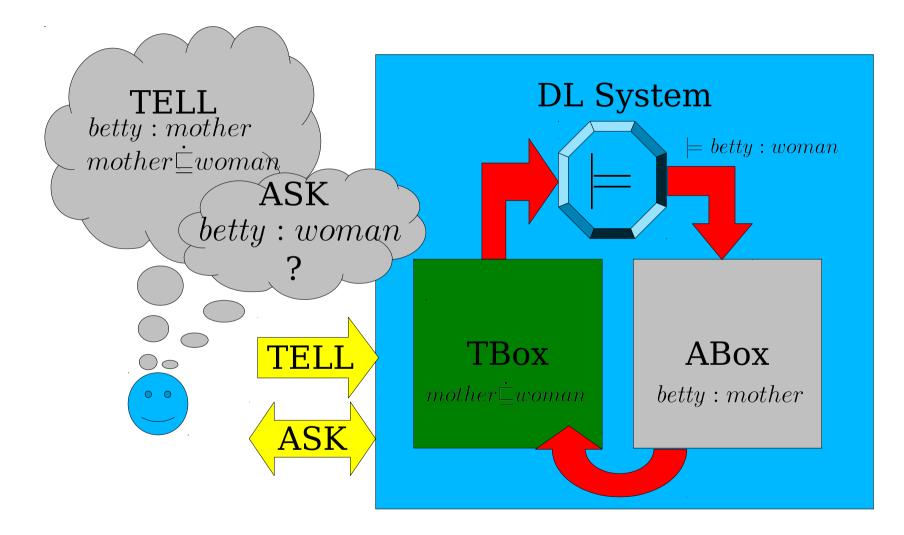


- Formal
 - suitable as **ontology** languages (Gruber definition)
- Well-understood
 - semantics, complexity, implemention techniques
- Family
 - somplexity scalable (e.g., lightweight DLs)
- Decidable
 - unlike FOPL
- Basis for Semantic Web (OWL2, ...)
- Many tools available

- Based on first order-logic
 - but variable-free and decidable
 - concept languages, class-based KR
- Central notions:
 - concept (OWL: class): unary predicate
 - role (OWL: property, RDF: predicate): binary predicate / relation
 - Abox individual: constant
 - Container data structures:
 - TBox: Set of terminological + role axioms: $C(x) \rightarrow D(x), C(x) \leftrightarrow D(x)$
 - ABox: individuals and relations: C(i), R(i,j)



Architecture of a DL System





- Abox satisfiability (w.r.t. a possibly empty TBox)
 - does the Abox have a model?

 $\{betty: \neg parent, betty: person, (betty, charles): has_child\}$

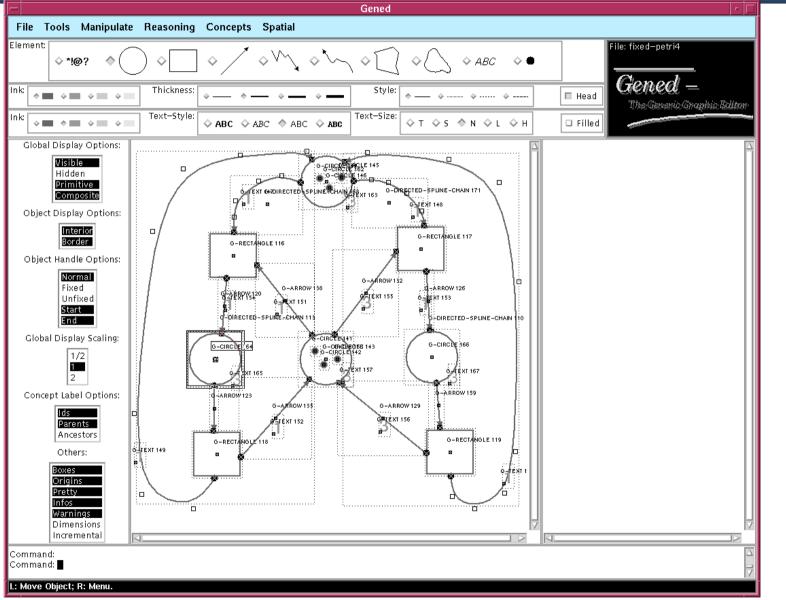
- Individual / ABox realization
 - compute the (most specific) concept names an individual is an instance of, e.g. in $\{betty : person, (betty, charles) : has_child\}$

it is realized that betty is an instance of parent

- Instance checking: is *betty* and instance of *parent*?
- Role filler checking: is *charles* a filler (successor) of the *has_child* role of *betty* ?

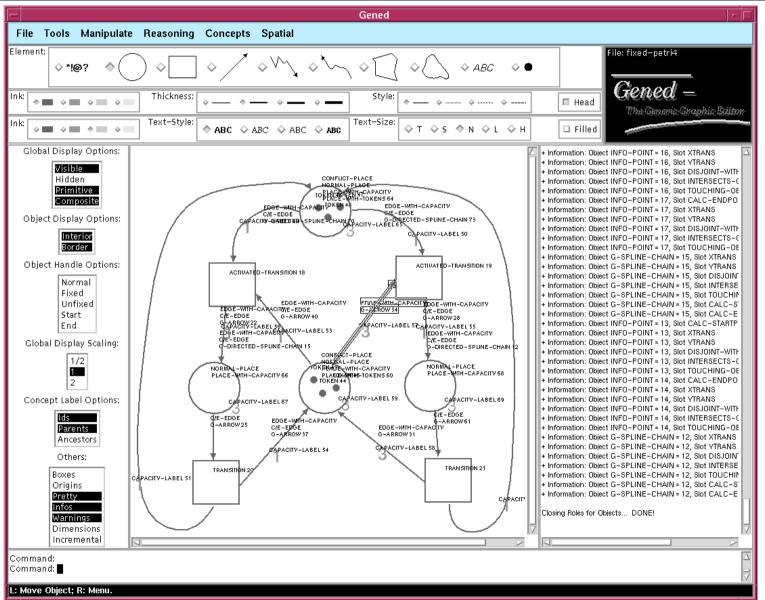


Recognition of Spatial Concepts (1996, Classic DL)





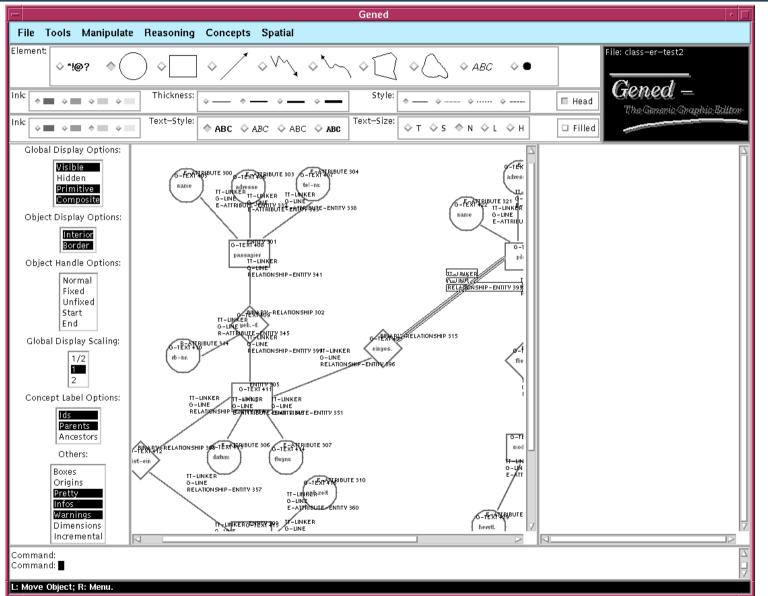
Petri Nets



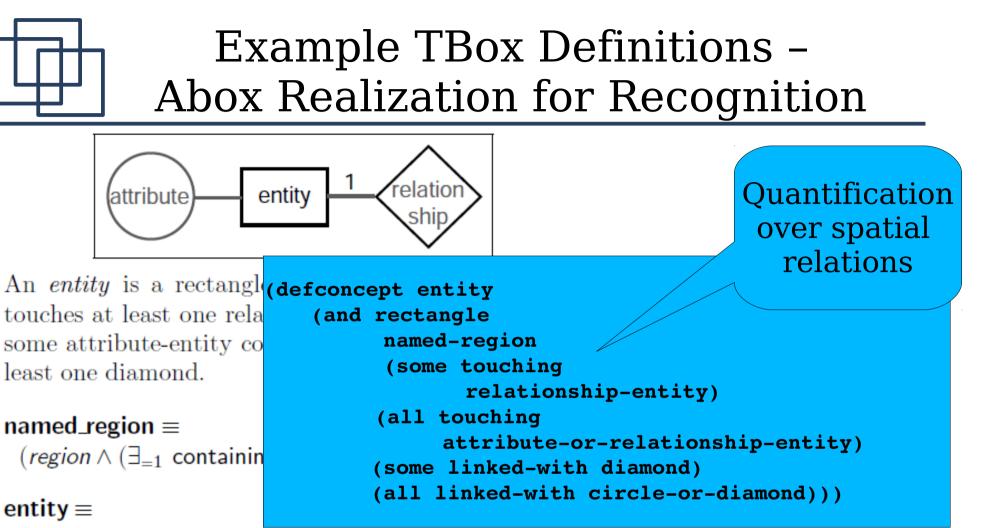
Michael Wessel



ER Diagrams



Michael Wessel

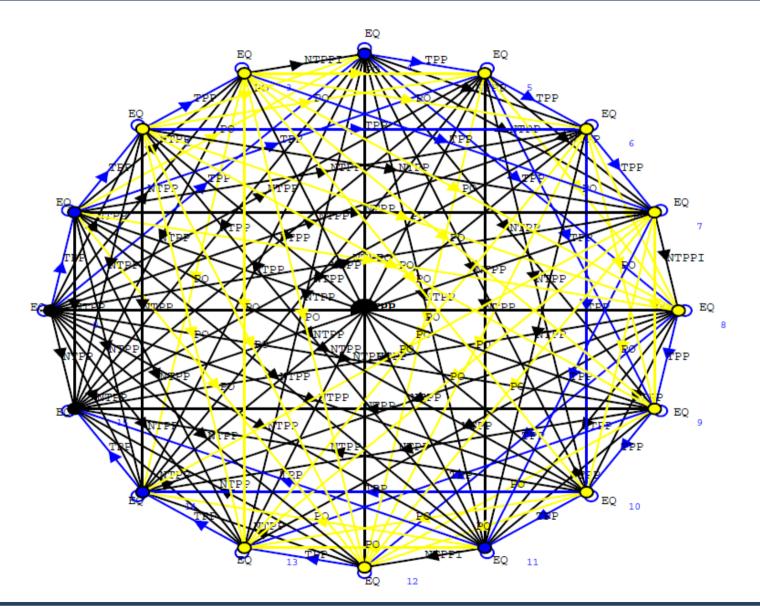


 $\begin{array}{ll} (rectangle \land named_region \land \\ (\exists_{\geq 1} \text{ touching relationship_entity}) \land \\ (\forall \text{ touching (attribute_entity \lor relationship_entity)}) \land \\ (\exists_{\geq 1} \text{ linked_with } diamond) \land \\ (\forall \text{ linked_with } (circle \lor diamond))) \end{array} \qquad \begin{array}{ll} \mathsf{C} \end{array}$

+ ABox for concrete diagram



ABoxes with Spatial Relations





- Inexpressivity of CLASSIC: hacks required (disjunction, qualified subroles, rules for "qualified subroles", ...) → motivation for Racer
- DL problem: we cannot recognize composite aggregates (e.g., whole ER diagrams or petri nets), only "placeholder individuals"
- CLASSIC performance: lots of spatial role relationships (disjoint!) \rightarrow 40 minutes for realization... \rightarrow motivation for Racer
- DL problem: open world assumption forall usually not satisfied
- Criticism why use DLs at all for that??
 - just used SQL queries or Datalog
 - we don't get the desired subsumption relationships between spatial concepts, as spatial relationships not properly axiomatized
 - \rightarrow work on spatial DLs

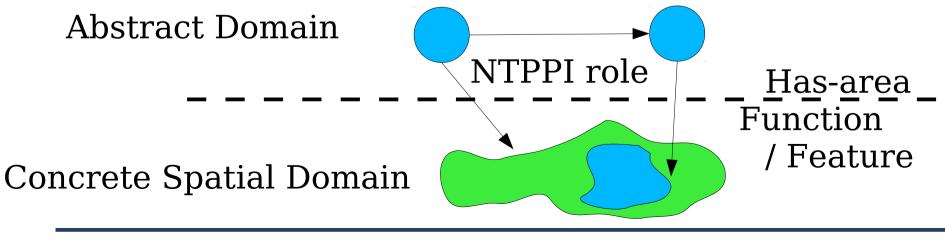


- Example of a desired subsumption relationship
 - Lake strictly contained in forest (NTPP)
 - House at (EC) lake strictly contained in forest not overlapping forest ("PO")
 - House at lake not overlapping forest
 is subconcept of house in forest

Quantification Over RCC relations



- Lutz, Moeller, Haarslev: $\mathcal{ALCRP}(\mathcal{S}_2)$
 - a DL with spatial concrete domains
 - concrete domain objects = spatial regions are connected to abstract domain objects of the DL via functions
 - properties between spatial objects induced roles / relations between corresponding abstract objects
 - the concrete geometry does not need to be known!





- Wessel
 - $\mathcal{ALCI}_{\mathcal{RCC}}$ family
 - DLs with complex role axioms of the form

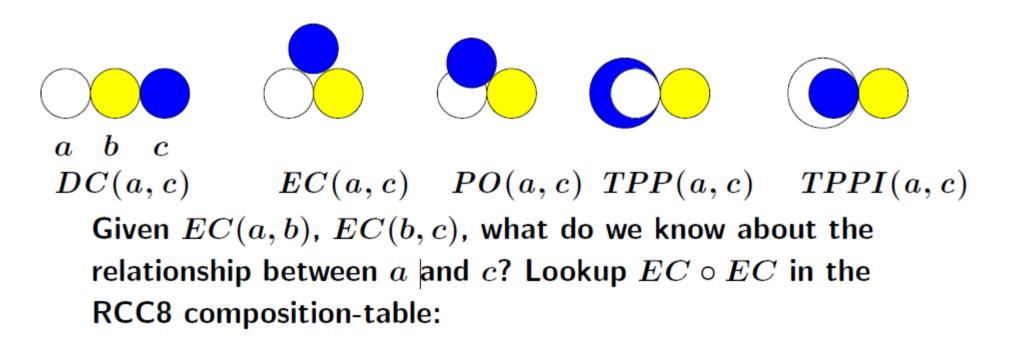
for all x,y,z : R(x,y) \land S(y,z) \rightarrow T1(x,z) \lor T2 ...

(undecidable in general)

- no concrete domains, but RCC relations axiomatized according to the RCC composition tables
- some decidable fragments found (Rcc1 ... Rcc3)
- RCC5 and RCC8 undecidable (Lutz + Wolter)



Composition Axioms



$$\begin{array}{l} \forall x, y, z : EC(x, y) \land EC(y, z) \Rightarrow \\ & (DC(x, z) \lor EC(x, z) \lor PO(x, z) \lor \\ & TPP(x, z) \lor TPPI(x, z)) \\ EC \circ EC \sqsubseteq DC \sqcup EC \sqcup PO \sqcup TPP \sqcup TPPI \end{array}$$

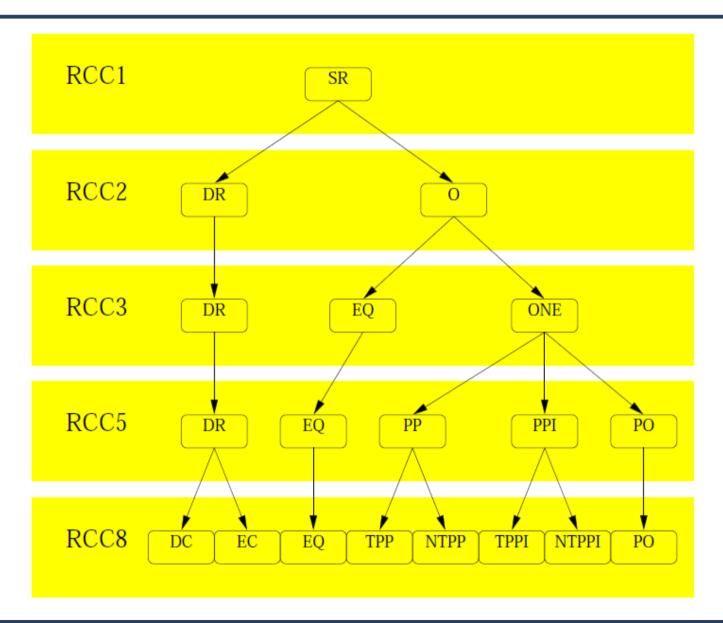


RCC8 Composition Table

RCC8	DC(a,b)	EC(a,b)	PO(a,b)	TPP(a,b)	NTPP(a,b)	TPPI(a,b)	NTPPI(a,b)	EQ(a,b)
DC(b,c)	•	DC EC PO TPPI NT- PPI DC	DC EC PO TPPI NT- PPI DC	DC	DC	DC EC PO TPPI NT- PPI	DC EC TPPI NT- PPI	DC
EC(b,c)	DC EC PO TPP NTPP	EC PO TPP TPPI EQ	DC EC PO TPPI NT- PPI	DC EC	DC	EC PO TPPI NT- PPI	PO TPPI NT- PPI	EC
PO(b,c)	DC EC PO TPP NTPP DC	DC EC PO TPP NTPP	•	DC EC PO TPP NTPP	DC EC PO TPP NTPP	PO TPPI NT- PPI	PO TPPI NT- PPI	РО
TPP(b,c)	DC EC PO TPP NTPP	EC PO TPP NTPP	PO TPP NTPP	TPP NTPP	NTPP	PO EQ TPP TPPI	PO TPPI NT- PPI	TPP
NTPP(b,c)	DC EC PO TPP NTPP	PO TPP NTPP	PO TPP NTPP	NTPP	NTPP	PO TPP NTPP	PO TPPI TPP NTPP NT- PPI EQ	NTPP
TPPI(b,c)	DC	DC EC	DC EC PO TPPI NT- PPI DC	DC EC PO TPP TPPI EQ DC	DC EC PO TPP NTPP	TPPI NT- PPI	NTPPI	TPPI
NTPPI(b,c)	DC	DC	EC PO TPPI NT- PPI	EC PO TPPI NT- PPI	•	NTPPI	NTPPI	NTPPI
EQ(b,c)	DC	EC	PO	TPP	NTPP	TPPI	NTPPI	EQ



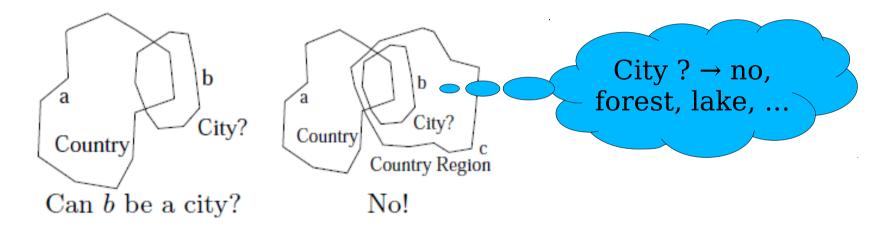
 $\mathcal{ALCI}_{\mathcal{RCC}}$ Family





2000: Image Interpretation with Default Rules and $\mathcal{ALCRP}(\mathcal{S}_2)$

- In real life image interpretation applications, "recognition by entailment (e.g., Abox realization)" does not work
- b is an unknown region what can it be?



- each city must be contained in exactly one country
- countries don't overlap \rightarrow b cannot be a city
- "Image Interpretation as Model Construction" (completion)
- or unsound reasoning, e.g., default rules that hypothesize



 $\begin{array}{l} country \doteq country_region \sqcap \forall contains.\neg country_region \sqcap \\ \forall overlaps.\neg country_region \sqcap \forall inside.\neg country_region \\ city \doteq city_region \sqcap \exists inside.country_region \\ lake \sqsubseteq lake_region \\ river \doteq river_region \sqcap \forall overlaps.\neg lake_region \sqcap \forall inside.\neg lake_region \\ \end{array}$

$$d_1 = \frac{area : city}{city}, \quad d_2 = \frac{area : lake}{lake}, \quad d_3 = \frac{area : country}{country}$$



2003 - Deductive GIS with DLs

- Lessons learned:
 - spatial reasoning on the intensional (Tbox) level too difficult if quantification over spatial relations permitted ...
 - ... or to inexpressive
 - \rightarrow work on the extensional level instead ;-)
 - many interesting problems on the extensional level too
 - large Aboxes many regions, many relations → use Racer (by then, Racer had a reputation of dealing well with large ABoxes)
 - to recognize spatial constellations: expressive Abox query language (\rightarrow nRQL)
 - spatio-thematic complex queries
 - hybrid system with, "on thy fly evaluation" of QSR from geometry, tightly integrated into a DL reasoner, …



DLMAPS – Hybrid Architecture

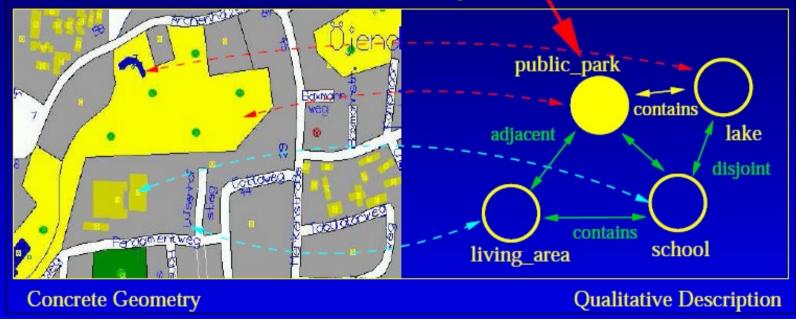
Query Component

- Simple Spatial Queries:
 - Retrieve all areas contained within this area
- Thematic Queries:
 - retrieve_concept_instances(lake)
- Spatio-thematic Queries: Retrieve all parks that contain a lake

Intensional Component

- "Concept definitions" / GEO–Ontology area, house, ...
- green_area -> area & ...
- lake -> area & (not green_area) ...
- park -> green_area & ...
- living_area -> area & (not green_area) ...
- park_wa_lake -> park & some cont. lake

Extensional Component

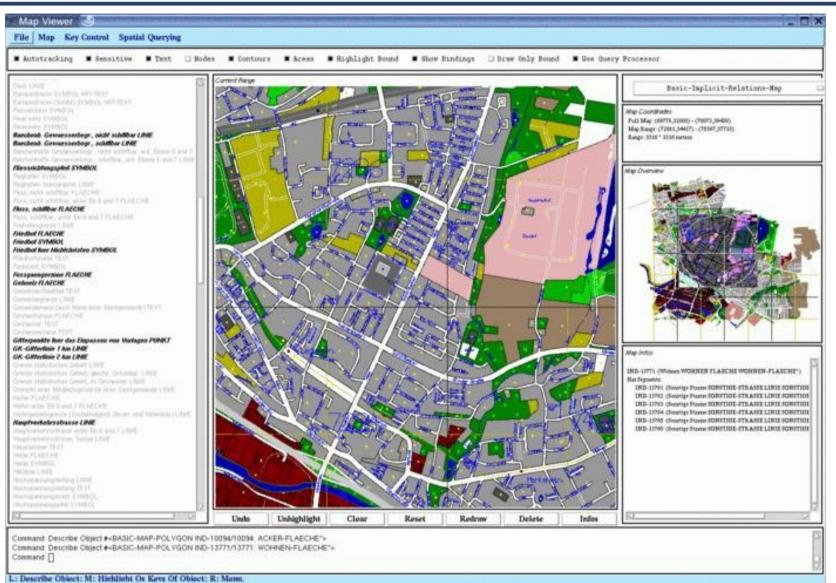




- hybrid: ?*x DL query atom, ?x spatial atom
- thematic, qualitative + quantiative spatial aspects
- composition-table based RCC reasoning
- cost-based optimizer (reused for "Abox-based" conjunctive queries in AURA)



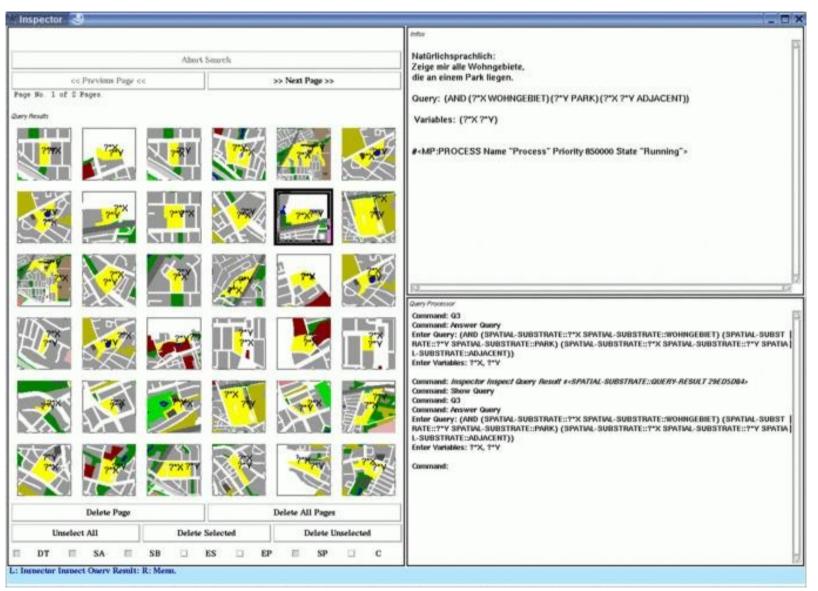
DLMAPS - Map Viewer



Michael Wessel



DLMAPS - Query Answering



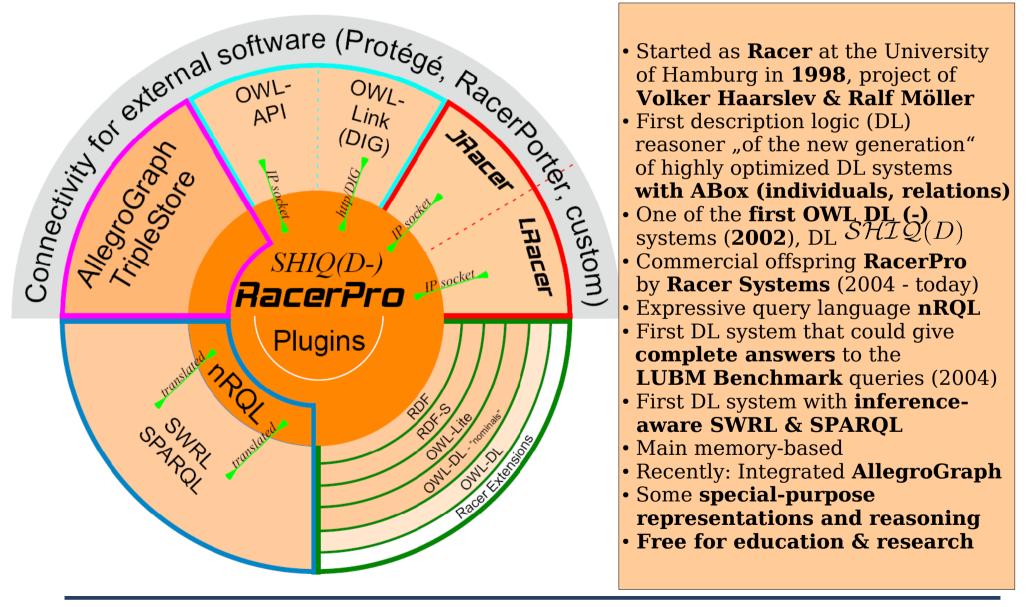




October 2004 - today



RacerPro - Architecture & History



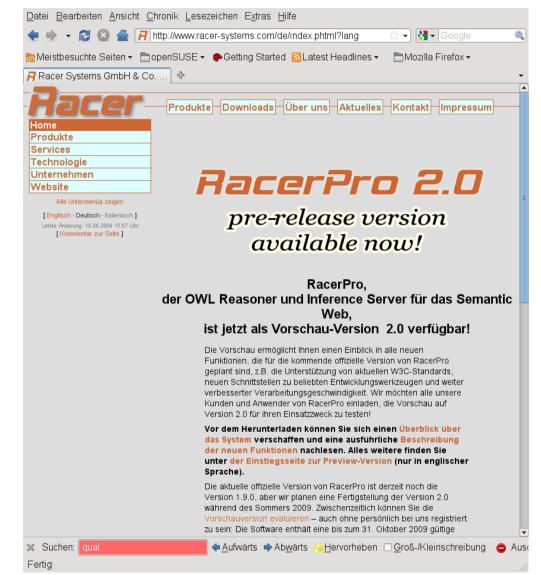


How Do I Get RacerPro ?

• www.racer-systems.com

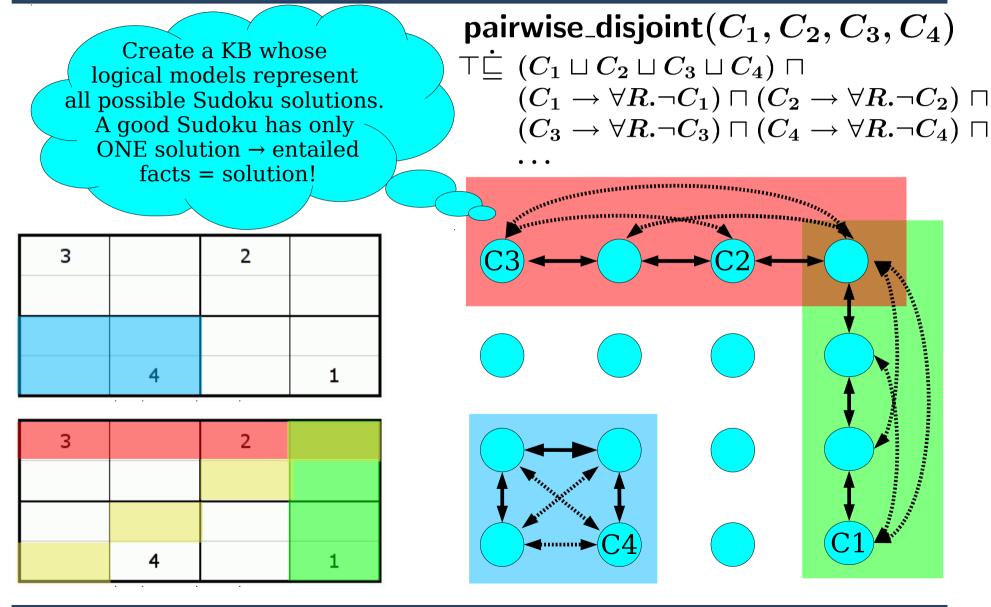
there is the 2.0 preview version

- no license required
- to be finalized soon
- Latest activities
 - Protege 4.3 plugin(Ulm / Derivo GmbH)
 - EL consequencebased reasoning
 - OntoLisp framework



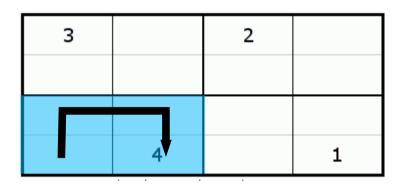


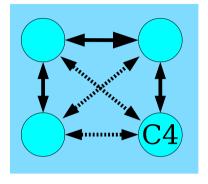
Solving Sudokus by Reasoning





Sudoku – ABox Construction



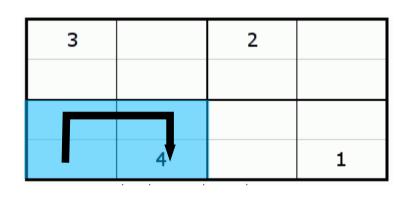


ABox construction

- by hand? OK for 4x4, but for 9x9?
 - → create the structure programmatically (MiniLisp)
- transitive & symmetric property \rightarrow
 - use different backward property instead of a symmetric property
 - quantification over common parent property
 - different props. for different rows, columns, diagonals

 $C_4
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Sudoku – Relational Structure



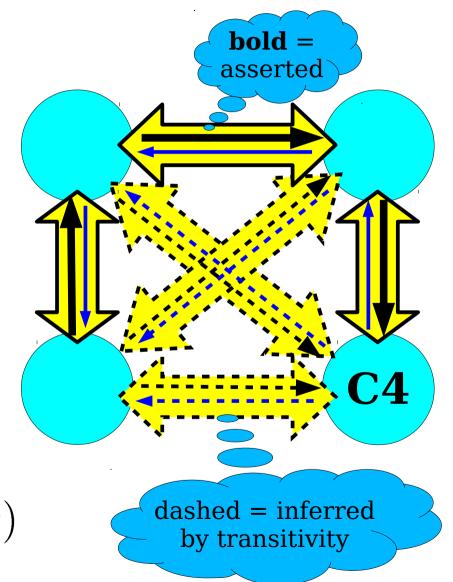
$$Q_1 \sqsubseteq R$$

$$Q_2 \sqsubseteq R$$

$$transitive(Q_1)$$

$$transitive(Q_2)$$

$$Q_1(x, y) \leftrightarrow Q_2(y, x)$$

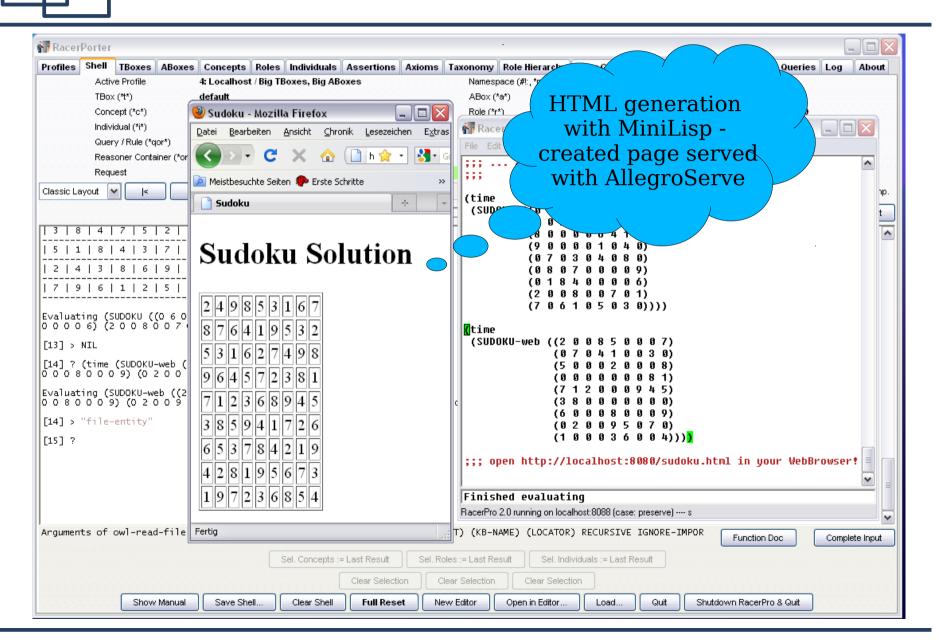




Solving Sudokus by Reasoning

RacerPorter	
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(here: ABox) creation, and 🔨	File Edit Buffer
output generation.	(terpri))
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	(t (format t "~%Bad Sudoku.")))))
functions can be defined in	
[13]? (time MiniLisp.	;;; Register new server functions
	(server-function sudoku-web)
	(server-function sudoku)
	;;; and use them! ;;;
	(time
	(SUDOKU ((060503208)
5 1 8 4 3 7 9 2 6	(105008003) (800006410)
2 4 3 8 6 9 7 5 1	(90001040) (070304080)
7 9 6 1 2 5 8 3 4	(08070009)
	(018400006) (200800701)
Evaluating (SUDOKU ((0 6 0 5 0 3 2 0 8) (1 0 5 0 0 8 0 0 3) (8 0 0 0 0 6 4 0 0 0 0 6) (2 0 0 8 0 0 7 0 1) (7 0 6 1 0 5 0 3 0))) took 0.2820 seconds.	(706105030))))
[13] > NIL	Finished evaluating
[14] ?	RacerPro 2.0 running on localhost:8088 (case: preserve) s
Arguments of owl-read-file: FILENAME &KEY (VERBOSE *TBOX-VERBOSE*) (INIT T) (KB-NAME) (LOCATOR) RECURSIVE IGNORE-IMPOR Function Doc Complete Input
Sel. Concepts := Last Result Sel. Roles	:= Last Result Sel. Individuals := Last Result
Clear Selection Clear	Selection Clear Selection
Show Manual Save Shell Clear Shell Full Reset New B	Editor Open in Editor Load Quit Shutdown RacerPro & Quit







Demos

- Sudoku
- People + Pets.owl Protege and RacerPorter
- JRacer + Eclipse
- LRacer...

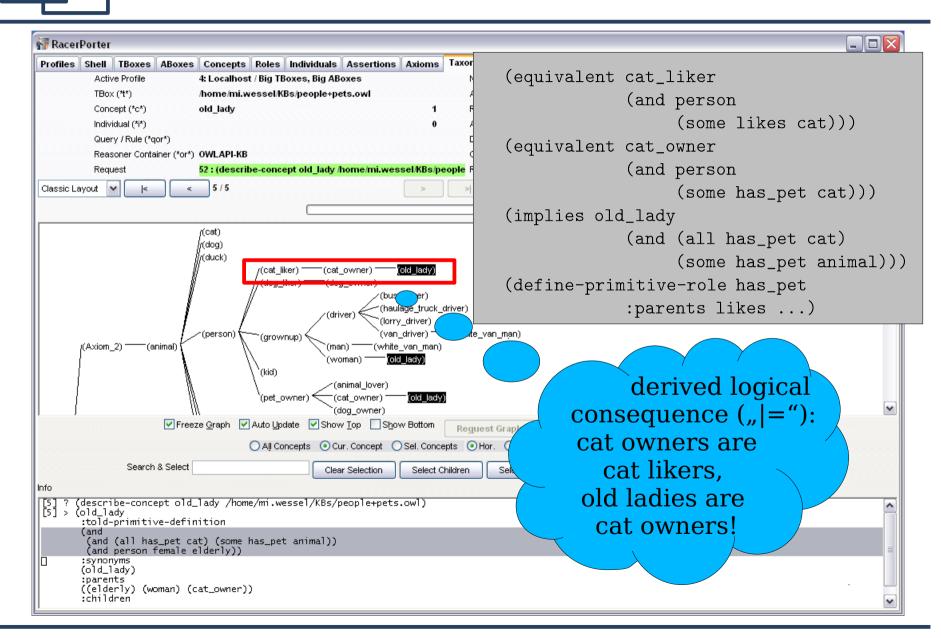
(2006 – today) RacerPorter – The Listener

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The Racer Editor with Some Example Queries

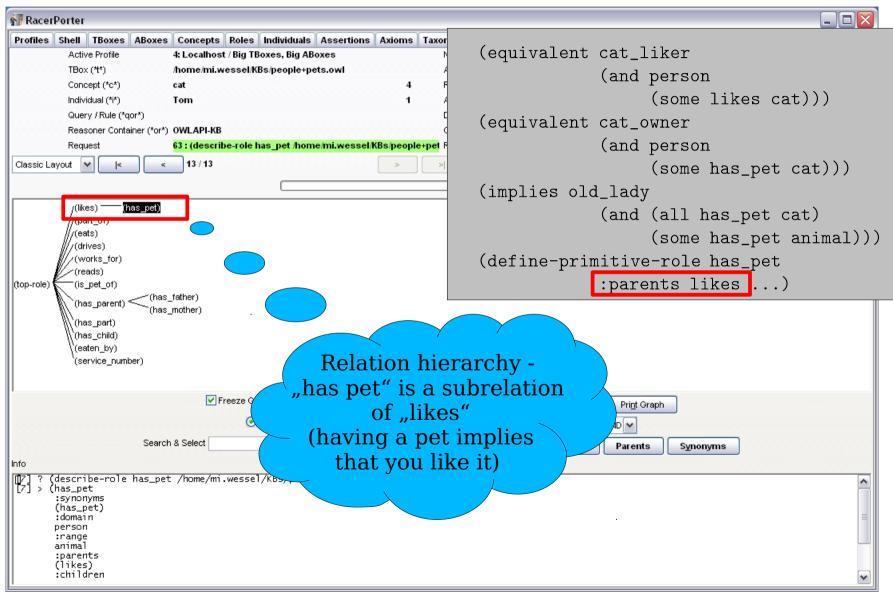
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Concept (*c*)	;;; multiple classification KRSS, SPAROL	
Individual (*i*)		
Query / Rule (*qor*)		
Reasoner Container (*or*) OWLAPI-KB	;;;; ABox Queries	
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	(concept-instances cat_owner)	st
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<pre>[*] > (:OKAY "RacerPro 2.0 running on localhost:8088 (case: present [*] > (:OKAY "RacerPro 2.0 running on localhost:8088</pre>		
[1] ? (get-racer-version) [1] > "2.0"	(and (?x cat_owner) (?x ?y has_pet)))	
<pre>[2] ? (full-reset) [2] > :okay-full-reset</pre>	(retrieve (?x ?y)	
[3] ? (racer-read-file "z:/temp/people+pets.racer")	(and (?x cat_owner) (?x ?y has pet)	
(in-tbox /home/mi.wessel/KBs/people+pets.owl size 124 role-size 2	('x 'y has_pet) ('y cat)))	
Duplicate definition (or animal (some part_of animal)) for Axiom_i 1/KBs/people+pets.owl)> /home/mi.wessel/KBs/people+pets.owl	(retrieve (?x ?y (direct-types ?y))	sse!
[3] > :0KAY	(and (?x pet_owner) (?x ?y has pet))	
[4] ? (retrieve (?x ?y) (and (?x cat_owner) (?x ?y has_pet) (?y c.	:dopt-chow-lambdac-p_t	
Concept (animal) causes a cycle in TBox /home/mi.wessel/KBs/people Concept (plant) causes a cycle in TBox /home/mi.wessel/KBs/people Concept (Nimar)		
Concept (Axiom_2) causes a cycle in TBox /home/mi.wessel/KBs/peop Classifying TBox	Finished evaluating	
Concept (mad_cow) is incoherent in TBox /home/mi.wessel/KBs/people	RacerPro 2.0 running on localhost:8088 (case: preserve) querie	
[4] > (((?x Minnie) (?y Tom)) ((?x Fred) (?y Tibbs)))		
[5] ?		
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Sel. Concepts := Last Result	Sel. Roles := Last Result Sel. Individuals := Last Result	
Clear Selection	Clear Selection Clear Selection	
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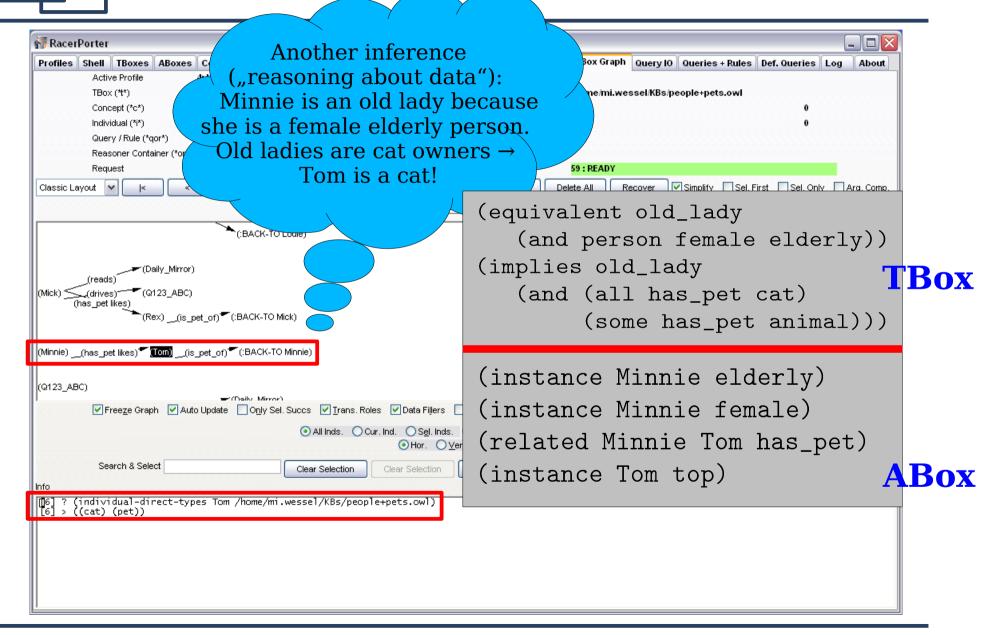




The Relation (Role / Property) Hierarchy



Individuals & Relationships – ABox Graph





Inspecting Class Assertions for Tom

🚮 Racer	Porter															
Profiles		TBoxes	ABoxes	Concepts	Roles	Individuals	Assertions	Axioms	Taxonomy	Role Hierard	hy ABox Gra	oh Query	IO Queries +	Rules Def	f. Queries	
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Relation ("Role") Assertions for Tom

🖣 Racer	Porter															
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- Old lady concept in...
 - KRSS / Racer native:

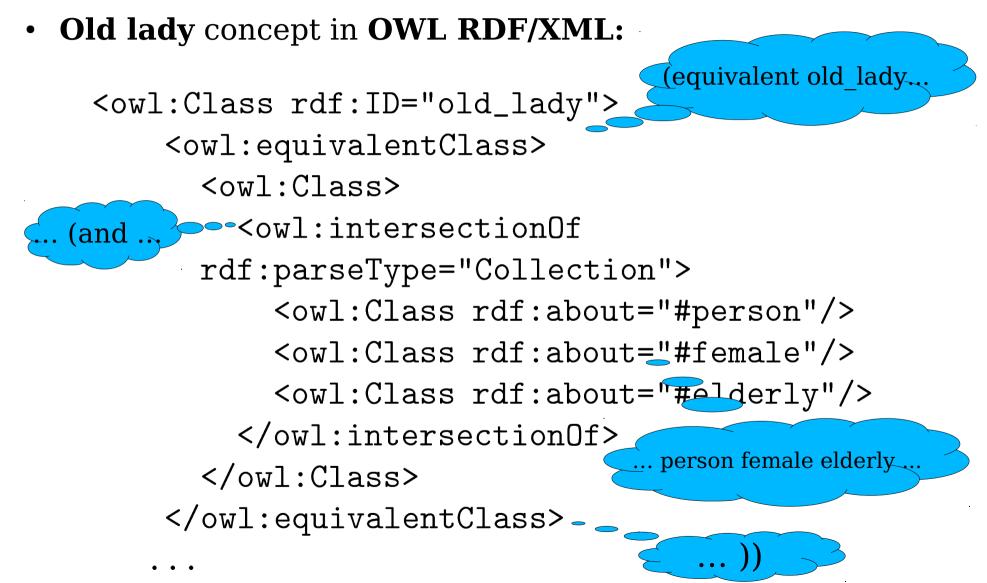
Racer has its own parsers

Syntaxes

- OWL 2 Functional Syntax (almost S-Expressions...)

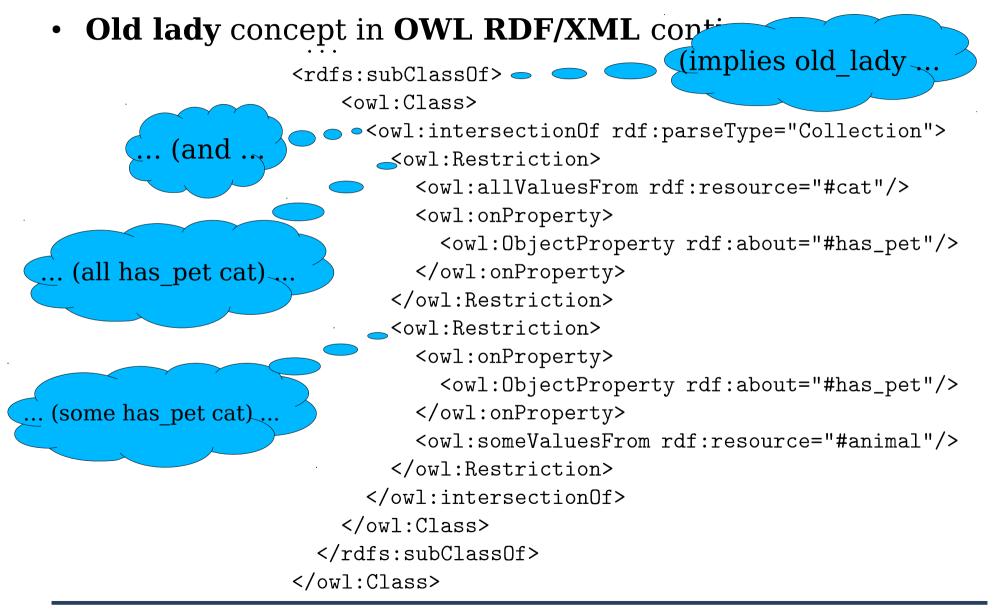
```
EquivalentClasses(
    old+lady
    ObjectIntersectionOf(female person elderly))
SubClassOf(old+lady
    ObjectIntersectionOf(
        ObjectAllValuesFrom(has_pet cat)
        ObjectSomeValuesFrom(has_pet animal)))
```







Syntaxes (3)





DOCOMO ContextWatcher / IYouIt



A mobile community service

- 1300+ users in 60+ countries
- Connected to emerging Web 2.0 services

Your digital life recorder

- Facilitating context awareness on standard phones
- Integration of key Semantic Web technologies

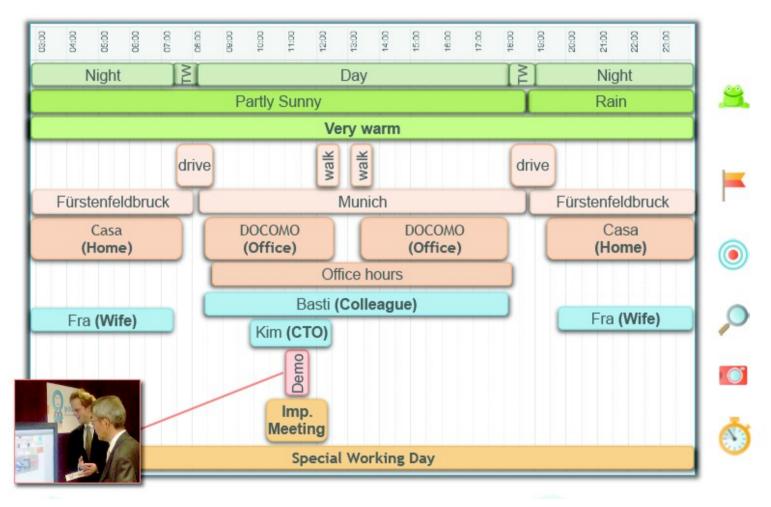








Towards a Life Browser





Regonized Events for "Life Logging" Blogging

ContextWatcher Blogs in 2005

FRIDAY, NOVEMBER 11, 2005

A busy ISWC day

Today was a busy ISWC day (84.1% covered). I took 9 pictures in Dublin and Galway.



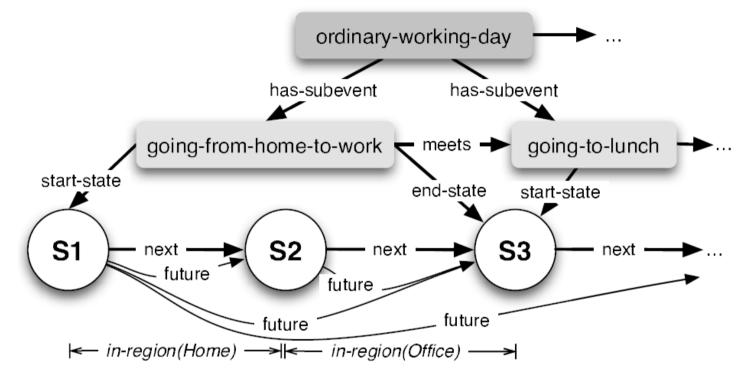


Today was the last day of my business trip to the ISWC'05 conference in Galway together with my colleague M. Luther. It was a cold and rainy day. In the afternoon I traveled back to Munich via Dublin by plane.

I visited Galway (51.8%), München (7.3%), Dublin (18.9%) and Offaly (9.9%), mainly Commute (5.2%) and ISWC (35.1%). I met luther (38.7%). My maximum speed was 131.2 km/h.

POSTED BY MATTHIAS AT 1:01 PM 0 COMMENTS

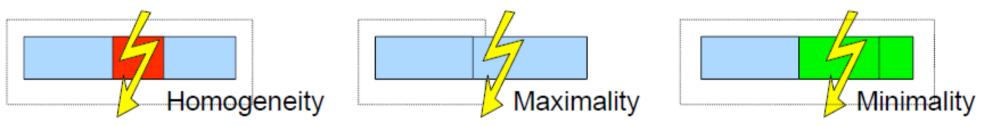
Situations, Simple & Complex Events



- States = situations \rightarrow simple events \rightarrow complex events
 - Linear time model (**next** role, transitive superrole **future**)
 - Allen temporal relation via concrete domain reasoning
 - Event constructions (aggregates!) via forward chaining rules

Realization of Event Recognizers

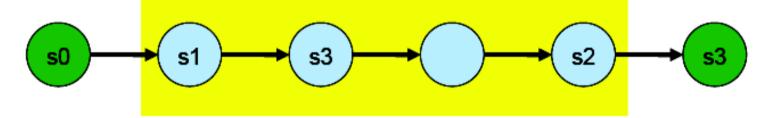
- Assuming events are already present as aggregates in the ABox, how to recognize them?
 - Defined concepts
 - Problems with relational expressivity for complex events
 - only tree-shaped temporal constraints expressible
 - Important event properties cannot be expressed (required for definitions of complex events!)



- Queries and rules
 - High relational expressivity over the ABox
 - Universal closed-domain quantifier (SPARQL, SQL, nRQL)

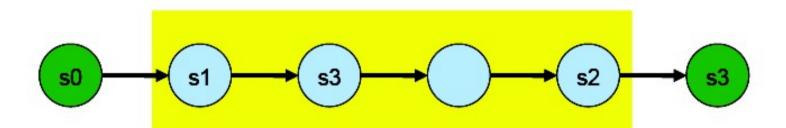
Recognizing Homogeneous Events (1)

$$ans(s_{1}, s_{2}) \leftarrow state(s_{1}), state(s_{2}), future(s_{1}, s_{2}), \\ P(s_{1}), P(s_{2}), \\ (\pi(s_{1}) \ (state(s_{0}), next(s_{0}, s_{1}), P(s_{0})), \\ (\pi(s_{2}) \ (state(s_{3}), next(s_{2}, s_{3}), P(s_{3})), \\ (\pi(s_{1}, s_{2}) \ (state(s_{3}), future(s_{1}, s_{3}), future(s_{3}, s_{2}), \\ (P(s_{3})) \end{cases}$$



Recognizing Homogeneous Events (2)

$$\begin{aligned} \mathcal{S}_{\mathcal{A}} = & (\Delta^{\mathcal{I}}, C^{\mathcal{I}}, ..., R^{\mathcal{I}}, ...), \text{ with} \\ & \Delta^{\mathcal{I}} = & \mathsf{inds}(\mathcal{A}), \\ & C^{\mathcal{I}} = \{ i \mid i \in \mathsf{inds}(\mathcal{A}), \mathcal{A} \models C(i) \} , \\ & R^{\mathcal{I}} = \{ (i, j) \mid \mathsf{inds}(\mathcal{A}), \mathcal{A} \models R(i, j) \}, \end{aligned}$$



$$\{ (s_1, s_2) \mid \exists s_1, s_2 : state(s_1) \land state(s_1) \land future(s_1, s_2) \land P(s_1) \land P(s_2) \land \\ \neg \exists s_0 : state(s_0) \land next(s_0, s_1) \land P(s_0) \land \\ \neg \exists s_3 : state(s_3) \land next(s_2, s_3) \land P(s_3) \land \\ \neg \exists s_3 : state(s_3) \land future(s_1, s_3), future(s_3, s_2) \land \\ \neg P(s_3) \}$$



BOEMIE Project – Interprete / Understand Athletics News Pages



Monday, 02 March 2009

Otto and Maresova notch jump victories in Dessau

Dessau, Germany - Björn Otto of Germany and Czech Oldriska Maresova took their events at the 8th Jumpers' Meeting in Dessau on Sunday (01) afternoon in front of about 1,500 spectators.

The winning heights were not quite what organisers and fans had hoped for. Oto took the Pole Vaule with S.60m and Marseova cleared 1.89m in the High Jump. But there were some very good attempts at greater heights, though none were ultimately successful. While the winners have not qualified for the upcoming European Indoor Championships they are both targeting the World Championships in Berlin this summer.

Men's Pole Vault -

5.60m proved to be the decisive height in Dessau's Anhalt Indoor Arena. While there were eight athletes still in contention only two were left when the bar was lifted to 5.70m: Otto, who had cleared the crucial height of 5.60m at his second attempt in convincing style, was in the lead while Russia's Viktor Chistiakov had passed this height after clearing 5.50m with plenty of room above the bar.

Tobias Scherbarth, who had convinced throughout the indoor season with the exception of the vital qualifier at the German indoors last week, was one of those who had promising attempts at S.Som, but finally had to settle for third with S.Som. Lars Birgeling also almost cleared S.GOm, but had to settle for fourth with S.4Om. After the dramatic competition at the German indoors in Leipzig eight days earlier it became obvious that the national pole vaulters lacked some tension.

Not so Otto, who had very good first and third attempts at 5.70m – a height which he had not cleared this winter. Together with his 5.60m jump these three jumps had looked as in his best times two years ago, when Otto had won a silver medal at the European Indoors. This time in Turin he will not be able to compete.

RELATED CONTENT

Bjorn Otto of Germany in action in the Men's Pole Vault Final

(Getty Images)

"But my indoor season gives me confidence regarding the summer, when I want to be back in peak form and qualify for the World Championships," Otto said. "It was good to see that it was getting better and better during this indoor season. It was important to get confidence back after my Achilles tendon operation last year."

Women's High Jump -

Three women were left in competition when 1.89m had to be cleared: Maresova had cleared all her other heights of 1.75 m, 1.80m and 1.85m at her first attempts. Germany's Aileen Herrmann and Bulgaria's Mirela Demireva had not been that convincing, but managed to jump 1.85m at their final attempts. But for Herrmann and Demireva 1.89m was too high on Sunday. Demireva settled for third and Herrmann took second while Maresova di clear 1.89m at her third attempt.

The 22-year-old Czech from Prague then went on for 1.92m, which would have been a personal best. So far she had jumped 1.90m this indoor season in Brno. Particularly her third attempt at 1.92m was a very good one and she was a bit unlucky that the bar came down.

"It was very close today," said Maresova, who will resume her indoor season with two national meetings in mid March. While she has not managed to qualify for Turin Maresova is optimistic concerning Berlin.

*I will have to jumn 1.95m to qualify for the World Championshins. I am ontimistic of reaching that goal, because there is not that

Fertig



use clues from different modalities (text, image, video, sound) and named entity recognition + background **KB** with athletics knowledge to interprete. Hypothesize and integrate (fusion). Label the paragraphs appropriately ("text understanding").

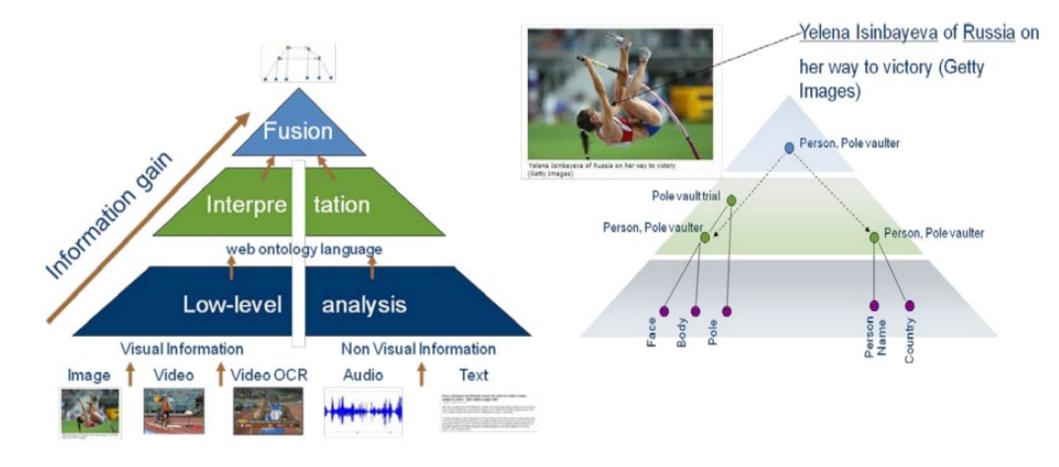


23.06.13

Michael Wessel



BOEMIE Project - "DIKW" Pyramid



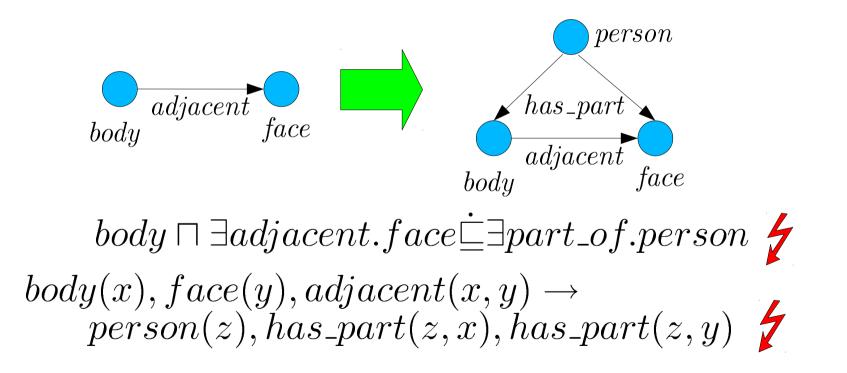


BOEMIE Project - Text Modality

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9th IAAF World Championships in Athle Denis (23 ? 31 August 2003).	skporpan
	witzerland ?
Cloete and Ayhan to headline again	juashed any
	Live from Zurish JAAF Colden League
Hestrie Cloete and S?rewa Ayhan were the undoubted stars of last Sunday?s ISTAF	- Live from Zurich - IAAF Golden League auotes
Golden League meeting in Berlin, and the	Fri 15 Aug 2003
South African World High Jump champion and	15 August 2003 - "Zurich is just magical. I have been winning every year since 1993
the <u>Turkish</u> European <u>1500m gold</u> medallist are sure to be headlining again in <u>Zurich</u> . S? <u>rewa Avhan</u>	here and today
wins in ISTAF	- Zurich offers high profile dress rehearsal for
Cloete with a practically unblemished score (Getty Images)	Paris Worlds
card up to and including her 2.05 m African	Fri 15 Aug 2003
record in <u>Berlin</u> , will have a World record <u>2.10</u> clearance in her sights once more today. Wearing the ?210? bib number on her	15 August 2003 ? Zurich, Switzerland ? The 'who?s who' of world athletics has once
vest last Sunday was perhaps too weighty a burden to carry as her	again convened
three heavily failed attempts proved but that height is surely within	

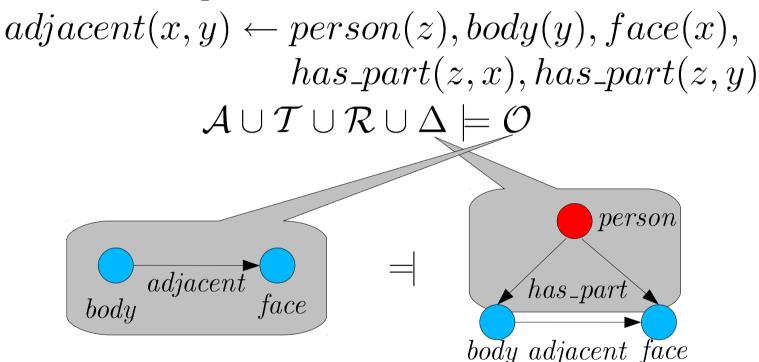


- The low-level annotations are incomplete
 - no person instance, but face & body region adjacency
 - often, aggregates must be instantiated, which is challenging





 abductive horn rules which "explain observations" (Shanahan) – implemented in nRQL

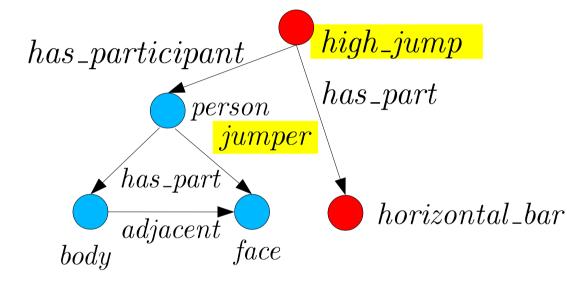


In general, more than one explanation possible

- minimality, consistency, preference, specificity
- probabilistic ranking (→ CASAM project)



Apply rules until fixpoint is reached

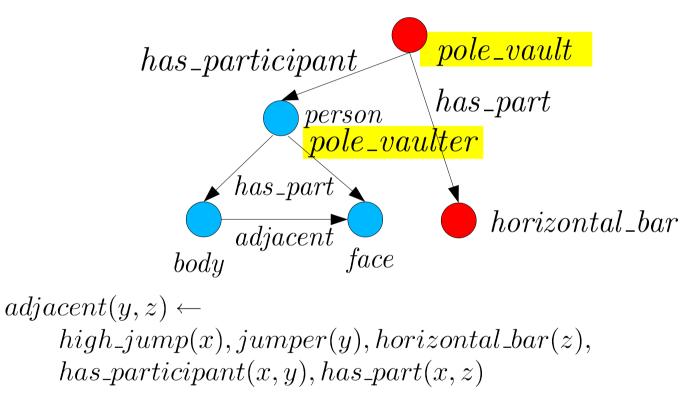


 $\begin{array}{l} adjacent(y,z) \leftarrow \\ high_jump(x), jumper(y), horizontal_bar(z), \\ has_participant(x,y), has_part(x,z) \end{array}$

 $\begin{array}{l} adjacent(y,z) \leftarrow \\ pole_vault(x), pole_vaulter(y), horizontal_bar(z), \\ has_participant(x,y), has_part(x,z) \end{array}$



Apply rules until fixpoint is reached



 $\begin{array}{l} adjacent(y,z) \leftarrow \\ pole_vault(x), pole_vaulter(y), horizontal_bar(z), \\ has_participant(x,y), has_part(x,z) \end{array}$



- Geo-spatial semantic web:
 - GeoSPARQL + Open Street Map + Map Server + Big Data + SemWeb → spatially aware semantic web → smarter SIRI, smarter QA, ...
- I would like to participate in any project on logicbased image or scene understanding
 - some experience
 - probabilistic ranking of hypotheses (CASAM)
 - MARKO Description Logic + Rules
- Racer is still the best environment for Lisp-based ontology and SemWeb development
 - integration with Franz Allegro Graph technology